

# Probabilistic generative models

## Linear models for classification

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# Probabilistic generative models

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generative models

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Models with linear decision boundaries arise from assumptions about the data

In the generative approach to classification, we firstly model the class-conditional densities  $p(\mathbf{x}|\mathcal{C}_k)$  and the class priors  $p(\mathcal{C}_k)$

- Then, we compute posterior probabilities  $p(\mathcal{C}_k|\mathbf{x})$  through Bayes' rule

## Probabilistic generative models (cont.)

### Remark

For two-class problems, the posterior probability of class  $\mathcal{C}_1$  can be written as

$$p(\mathcal{C}_1|\mathbf{x}) = \frac{p(\mathbf{x}|\mathcal{C}_1)p(\mathcal{C}_1)}{\underbrace{p(\mathbf{x}|\mathcal{C}_1)p(\mathcal{C}_1) + p(\mathbf{x}|\mathcal{C}_2)p(\mathcal{C}_2)}_{p(\mathbf{x}) = \sum_k p(\mathbf{x}, \mathcal{C}_k) = \sum_k p(\mathbf{x}|\mathcal{C}_k)p(\mathcal{C}_k)}} = \frac{1}{1 + \exp[-a(\mathbf{x})]} = \sigma[a(\mathbf{x})] \quad (1)$$

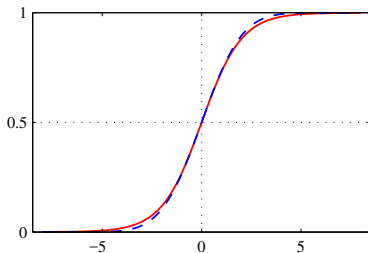
where we defined

$$a(\mathbf{x}) = \ln \frac{p(\mathbf{x}|\mathcal{C}_1)p(\mathcal{C}_1)}{p(\mathbf{x}|\mathcal{C}_2)p(\mathcal{C}_2)} \quad (2)$$

$\sigma(a)$  is the **logistic sigmoid function** (plotted in red)

$$\sigma(a) = \frac{1}{1 + \exp(-a)} \quad (3)$$

or **squashing function**, because it maps  $\mathbb{R}$  onto a finite interval



## Probabilistic generative models (cont.)

The logistic sigmoid satisfies the following symmetry property

$$\sigma(-a) = 1 - \sigma(a) \quad (4)$$

The inverse of the logistic sigmoid is known as **logit function**

$$a = \ln \left( \frac{\sigma}{1 - \sigma} \right) \quad (5)$$

It reflects the log of the ratio of probabilities for two classes

$$\ln \frac{p(C_1|\mathbf{x})}{p(C_2|\mathbf{x})}$$

## Probabilistic generative models (cont.)

$$\begin{aligned}
 p(C_1|\mathbf{x}) &= \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_1)p(C_1) + p(\mathbf{x}|C_2)p(C_2)} \\
 &= \frac{1}{1 + \exp\left(-\underbrace{\ln \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_2)p(C_2)}}_{a(\mathbf{x})}\right)} \\
 &= \sigma\left(\underbrace{\ln \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_2)p(C_2)}}_{a(\mathbf{x})}\right)
 \end{aligned}$$

We have written the posterior probabilities in an equivalent form that will have significance when  $a(\mathbf{x})$  is a linear function of  $\mathbf{x}$

- Then, the posterior probability can be explicitly governed by a generalised linear model

For the case  $K > 2$  classes, we have

$$p(C_k|\mathbf{x}) = \frac{p(\mathbf{x}|C_k)p(C_k)}{\sum_{j=1}^K p(\mathbf{x}|C_j)p(C_j)} = \frac{\exp[a_k(\mathbf{x})]}{\sum_{j=1}^K \exp[a_j(\mathbf{x})]} \quad (6)$$

known as **normalised exponential**<sup>1</sup>

We have defined the quantity  $a_k(\mathbf{x})$  as

$$a_k(\mathbf{x}) = \ln [p(\mathbf{x}|C_k)p(C_k)] \quad (7)$$

If  $a_k \gg a_j$ , for all  $j \neq k$ , then  $\begin{cases} p(C_k|\mathbf{x}) \simeq 1 \\ p(C_j|\mathbf{x}) \simeq 0 \end{cases}$

We are interested in the consequences of choosing some specific forms for the class-conditional densities  $p(C_k|\mathbf{x})$

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<sup>1</sup>It is a generalisation of the logistic sigmoid and it is also known as the softmax function

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# Continuous inputs

## Probabilistic generative models

Let us assume that the class-conditional densities  $p(\mathbf{x}|C_k)$  are Gaussian

$$p(\mathbf{x}|C_k) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_k)^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu}_k)\right) \quad (8)$$

The Gaussians have different means  $\boldsymbol{\mu}_k$  but share covariance matrix  $\Sigma$

We want to explore the form of the posterior probabilities  $p(C_k|\mathbf{x})$

## Continuous inputs (cont.)

$$\begin{aligned}
 p(C_1|\mathbf{x}) &= \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_1)p(C_1) + p(\mathbf{x}|C_2)p(C_2)} = \frac{1}{1 + \exp\left(-\underbrace{\ln \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_2)p(C_2)}}_{a(\mathbf{x})}\right)} \\
 &= \sigma\left(\underbrace{\ln \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_2)p(C_2)}}_{a(\mathbf{x})}\right) \\
 &= \sigma(\mathbf{w}^T \mathbf{x} + w_0)
 \end{aligned} \tag{9}$$

where

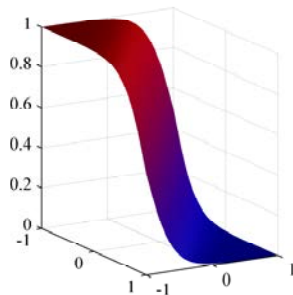
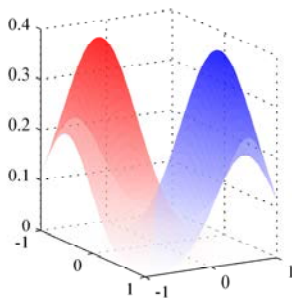
$$\mathbf{w} = \Sigma^{-1}(\mu_1 - \mu_2) \tag{10}$$

$$w_0 = -\frac{1}{2}\mu_1^T \Sigma^{-1} \mu_1 + \frac{1}{2}\mu_2^T \Sigma^{-1} \mu_2 + \ln \frac{p(C_1)}{p(C_2)} \tag{11}$$

The quadratic terms in  $\mathbf{x}$  from the exponents of the Gaussian densities have cancelled (due to the assumption of common covariance matrices) leading to

- a linear function of  $\mathbf{x}$  in the argument of the logistic sigmoid

The left-hand plot shows the class-conditional densities for two classes over  $2D$



The posterior probability  $p(C_1|\mathbf{x})$  is a logistic sigmoid of a linear function of  $\mathbf{x}$

The surface in the right-hand plot is coloured using a proportion of red given by  $p(C_1|\mathbf{x})$  and a proportion of blue given by  $p(C_2|\mathbf{x}) = 1 - p(C_1|\mathbf{x})$

# Continuous inputs (cont.)

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Decision boundaries are surfaces with constant posterior probabilities  $p(C_k|\mathbf{x})$

- Linear functions of  $\mathbf{x}$
- Linear in input space

Prior probabilities  $p(C_k)$  enter only through the bias parameter  $w_0$ , changes in priors have the effect of making parallel shifts of the decision boundary

- More generally, of the parallel contours of constant posterior probability

## Continuous inputs (cont.)

For the  $K$ -class case, using  $p(\mathcal{C}_k|\mathbf{x}) = \frac{p(\mathbf{x}|\mathcal{C}_k)p(\mathcal{C}_k)}{\sum_{j=1}^K p(\mathbf{x}|\mathcal{C}_j)p(\mathcal{C}_j)} = \frac{\exp(a_k)}{\sum_{j=1}^K \exp(a_j)}$

and  $a_k = \ln(p(\mathbf{x}|\mathcal{C}_k)p(\mathcal{C}_k))$ , we have

$$a_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0} \quad (12)$$

$$\mathbf{w}_k = \Sigma^{-1} \boldsymbol{\mu}_k \quad (13)$$

$$w_{k0} = -\frac{1}{2} \boldsymbol{\mu}_k^T \Sigma^{-1} \boldsymbol{\mu}_k + \ln p(\mathcal{C}_k) \quad (14)$$

The  $a_k(\mathbf{x})$  are again linear functions of  $\mathbf{x}$  as a consequence of the cancellation of the quadratic terms due to the shared covariances

# Continuous inputs (cont.)

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The resulting decision boundaries (minimum misclassification rate) occur when two of the posterior probabilities (the two largest) are equal, and so they are defined by linear functions of  $x$

- Again, we have a generalised linear model

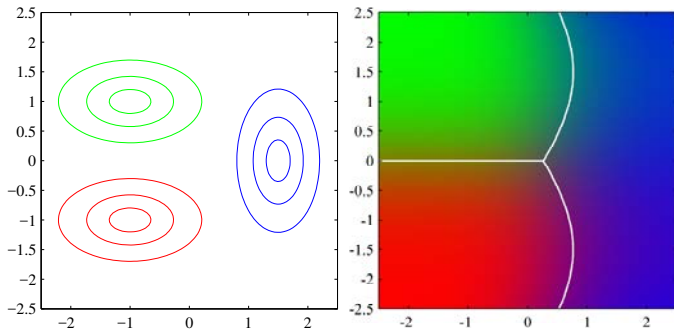
If we relax the assumption of a shared covariance matrix and allow each class-conditional density  $p(\mathbf{x}|\mathcal{C}_k)$  to have its own covariance matrix  $\Sigma_k$ ,

- then the earlier cancellations no longer occur, and we will obtain quadratic functions of  $\mathbf{x}$ , giving rise to a **quadratic discriminant**



Class-conditional densities for three classes each having a Gaussian distribution

- red and green classes have the same covariance matrix



The corresponding posterior probabilities and the decision boundaries

- Linear boundary between red and green classes, same covariance matrix
- Quadratic boundaries between other pairs, different covariance matrix

# Maximum likelihood solution

## Probabilistic generative models

# Maximum likelihood solution

Once we specified a parametric functional form for class-conditional densities  $p(\mathbf{x}|\mathcal{C}_k)$ , we can determine parameters and prior class probabilities  $p(\mathcal{C}_k)$

- Maximum likelihood

This requires data comprising observations of  $\mathbf{x}$  and corresponding class labels

Consider first the two-class case, each having a Gaussian density with shared covariance matrix  $\Sigma$ , and suppose we have data  $\{\mathbf{x}_n, t_n\}_{n=1}^N$

$$\begin{cases} t_n = 1, & \text{for } \mathcal{C}_1 \text{ with prior probability } p(\mathcal{C}_1) = \pi \\ t_n = 0, & \text{for } \mathcal{C}_2 \text{ with prior probability } p(\mathcal{C}_2) = 1 - \pi \end{cases}$$

For a data point  $\mathbf{x}_n$  from class  $\mathcal{C}_1$  ( $\mathcal{C}_2$ ), we have  $t_n = 1$  ( $t_n = 0$ ), thus

$$\begin{aligned} p(\mathbf{x}_n, \mathcal{C}_1) &= p(\mathcal{C}_1)p(\mathbf{x}_n|\mathcal{C}_1) = \pi\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_1, \boldsymbol{\Sigma}) \\ p(\mathbf{x}_n, \mathcal{C}_2) &= p(\mathcal{C}_2)p(\mathbf{x}_n|\mathcal{C}_2) = (1 - \pi)\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_2, \boldsymbol{\Sigma}) \end{aligned}$$

For  $\mathbf{t} = (t_1, \dots, t_n)^T$ , the likelihood function is given by

$$p(\mathbf{t}, \mathbf{X}|\pi, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \boldsymbol{\Sigma}) = \prod_{n=1}^N \left( \pi\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_1, \boldsymbol{\Sigma}) \right)^{t_n} \left( (1 - \pi)\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_2, \boldsymbol{\Sigma}) \right)^{1-t_n} \quad (15)$$

## Maximum likelihood solution (cont.)

As usual, we maximise the log of the likelihood function

$$\sum_{n=1}^N \underbrace{t_n \ln(\pi) + (1 - t_n) \ln(1 - \pi)}_{\pi} + \underbrace{t_n \ln(\mathcal{N}(\mathbf{x}_n | \mu_1, \Sigma))}_{\mu_1, \Sigma} + \underbrace{(1 - t_n) \ln(\mathcal{N}(\mathbf{x}_n | \mu_2, \Sigma))}_{\mu_2, \Sigma} \quad (16)$$

$$\underbrace{\hspace{15em}}_{\mu_1, \mu_2, \Sigma}$$

# Maximum likelihood solution (cont.)

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Consider first maximisation with respect to  $\pi$ , where the terms on  $\pi$  are

$$\sum_{n=1}^N \left( t_n \ln(\pi) + (1 - t_n) \ln(1 - \pi) \right) \quad (17)$$

Setting the derivative wrt  $\pi$  to zero and rearranging

$$\pi = \frac{1}{N} \sum_{n=1}^N t_n = \frac{N_1}{N} = \frac{N_1}{N_1 + N_2} \quad (18)$$

## Remark

The maximum likelihood estimate for  $\pi$  is the fraction of points in  $\mathcal{C}_1$

# Maximum likelihood solution (cont.)

Now consider maximisation with respect to  $\mu_1$ , where the terms on  $\mu_1$  are

$$\sum_{n=1}^N t_n \ln \left( \mathcal{N}(\mathbf{x}_n | \mu_1, \Sigma) \right) = -\frac{1}{2} \sum_{n=1}^N t_n (\mathbf{x}_n - \mu_1)^T \Sigma^{-1} (\mathbf{x}_n - \mu_1) + \text{const} \quad (19)$$

Setting the derivative wrt  $\mu_1$  to zero and rearranging

$$\mu_1 = \frac{1}{N_1} \sum_{n=1}^N t_n \mathbf{x}_n \quad (20)$$

## Remark

The maximum likelihood estimate of  $\mu_1$  is the mean of inputs  $\mathbf{x}_n$  in class  $\mathcal{C}_1$

$$\mu_2 = \frac{1}{N_2} \sum_{n=1}^N t_n \mathbf{x}_n \quad (21)$$

## Maximum likelihood solution (cont.)

Lastly consider maximisation with respect to  $\Sigma$ , where the terms on  $\Sigma$  are

$$\begin{aligned}
 & -\frac{1}{2} \sum_{n=1}^N t_n \ln |\Sigma| - \frac{1}{2} \sum_{n=1}^N t_n (\mathbf{x}_n - \boldsymbol{\mu}_1)^T \Sigma^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_1) \\
 & -\frac{1}{2} \sum_{n=1}^N (1 - t_n) \ln |\Sigma| - \frac{1}{2} \sum_{n=1}^N (1 - t_n) (\mathbf{x}_n - \boldsymbol{\mu}_2)^T \Sigma^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_2) \\
 & = -\frac{N}{2} \ln |\Sigma| - \frac{N}{2} \text{Tr}(\Sigma^{-1} \mathbf{S}) \quad (22)
 \end{aligned}$$

where

$$\mathbf{S} = \frac{N_1}{N} \mathbf{S}_1 + \frac{N_2}{N} \mathbf{S}_2 \quad (23)$$

$$\mathbf{S}_1 = \frac{1}{N_1} \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \boldsymbol{\mu}_1)(\mathbf{x}_n - \boldsymbol{\mu}_1)^T \quad (24)$$

$$\mathbf{S}_2 = \frac{1}{N_2} \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \boldsymbol{\mu}_2)(\mathbf{x}_n - \boldsymbol{\mu}_2)^T \quad (25)$$



# Maximum likelihood solution (cont.)

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$$\Sigma = \mathbf{S} = \frac{N_1}{N} \frac{1}{N_1} \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \boldsymbol{\mu}_1)(\mathbf{x}_n - \boldsymbol{\mu}_1)^T + \frac{N_2}{N} \frac{1}{N_2} \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \boldsymbol{\mu}_2)(\mathbf{x}_n - \boldsymbol{\mu}_2)^T$$

Average of the covariance matrices associated with each class separately