

**Exercise 01.** Consider the linear time-invariant system given in SS representation

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \end{bmatrix} u(t)$$

$$y(t) = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

- Determine a new representation in which the new state variables are

$$\begin{aligned} z_1(t) &= x_1(t) + x_2(t); \\ z_2(t) &= x_1(t) - x_2(t); \end{aligned}$$

- Determine the corresponding similarity transformation  $\mathbf{z} = \mathbf{P}^{-1}\mathbf{x}$  and calculate all the system matrices in the new representation;
- In the original representation, let  $\mathbf{x}(0) = (4, 2)^T$ . Determine the state transition matrix and the force-free evolution of the system from  $\mathbf{x}(0)$ .

**Exercise 02.** Consider the linear time-invariant system given in SS representation

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} u_1(t) \\ u_2(t) \end{bmatrix}$$

$$y(t) = \begin{bmatrix} 5 & 2 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 0 & 7 \end{bmatrix} \begin{bmatrix} u_1(t) \\ u_2(t) \end{bmatrix}$$

Use the Sylvester's expansion to determine the state transition matrix and compute the force-free evolution from  $\mathbf{x}(0) = (1, 2)^T$ .